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# HYDRODYNAMIC FORCES ON TAINTER GATES AND STILLING BASIN OLD RIVER CONTROL AUXILIARY STRUCTURE

Hydraulic Model Investigation

by

B. P. Fletcher, J. L. Grace, Jr.

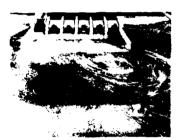
Hydraulic Laboratory

DEPARTMENT OF THE ARMY Waterways Experiment Station, Corps of Engineers PO Box 631, Vicksburg, Mississippi 39180-0631



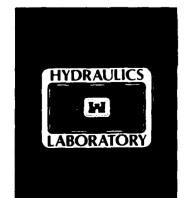


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The location, frequency, and magnitude ing basin apron were determined. Also tests on the baffles and end still. The measured cantly higher than drag forces computed from for research or site-specific studies to devedividual and collective forces acting on still	were conducte drag forces of drag coeffic elop design g	ed to detent the baffients. The	rmine the le blocks is indicat r determin	forces acting were signifi- ted the need
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#### 19. ABSTRACT (Continued).

Piezometers and electronic pressure cells were used to measure pressure distribution in the stilling basin. Water-surface profiles were obtained along the longitudinal center line of the stilling basin.

A skin plate covering the girders on the downstream side of the tainter gate prevented debris from accumulating on the gate. The skin plate did not alter the hydraulic loads on the tainter gate.

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#### **PREFACE**

The model investigation was authorized by the Office, Chief of Engineers (OCE), US Army on 13 January 1981 at the request of the US Army Engineer District, New Orleans.

The study was conducted in the Hydraulics Laboratory (HL) of the US Army Engineer Waterways Experiment Station (WES), Vicksburg, Mississippi, during the period January 1981 to August 1981 under the direction of Mr. H. B. Simmons, former Chief, HL, and under the general supervision of Messrs. J. L. Grace, Jr., former Chief, Hydraulic Structures Division (HSD), and N. R. Oswalt, Chief, Spillways and Channels Branch. Mr. F. A. Herrmann, Jr., Chief, HL. Project engineer for the model was Mr. B. P. Fletcher, HSD, Assisting were Messrs. P. Bhramayana and B. P. Perkins, HSD. This report was prepared by Messrs. Fletcher and Grace.

During the course of the investigation, Messrs. Rodney Resta, Henry G. Reed, Lawrence H. Cave, William Pinner, Loren Heiple, Victor M. Agostinelli, Roland J. Dubuission, Frank Weaver, Robert I. Kaufman, Estes Walker, Larry F. Cook, Henry S. Martin, and Lawrence A. Rabalias of the Lower Mississippi Valley Division; and Frederic M. Chatry, Bob Fairless, Bill Gwyn, Tom Johnson, Tom Hassenboehler, Jim Miles, Cecil Soileau, Tilden Dufrene, Steve Martin, and P. A. Becnel, Jr., of the New Orleans District visited WES to discuss the program of model tests and observe the model in operation.

Commander and Director of WES during the preparation and publication of this report was COL Dwayne G. Lee, CE. Technical Director was Dr. Robert W. Whalin.



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#### CONTENTS

	Page
PREFACE	1
CONVERSION FACTORS, NON-SI TO SI (METRIC) UNITS OF MEASUREMENT	3
PART I: INTRODUCTION	4
The Prototype Purpose of Investigation	
PART II: THE MODEL	6
Description Interpretation of Model Results	
PART III: TESTS AND RESULTS	8
System Response	8 9 9
PART IV: SUMMARY AND DISCUSSION OF RESULTS	14
TABLES 1-7	
FIGURES 1-14	

### CONVERSION FACTORS, NON-SI TO SI (METRIC) UNITS OF MEASUREMENT

Non-SI units of measurement used in this report can be converted to SI (metric) units as follows:

Multiply	Ву	To Obtain
cubic feet	0.02831685	cubic metres
feet	0.3048	metres
inches	25.4	millimetres
kips (force)	4448.222	newtons
kips (force) per foot	1.355818	metre kilonewtons
miles (US statute)	1.609344	kilometres

## HYDRODYNAMIC FORCES ON TAINTER GATES AND STILLING BASIN OLD RIVER CONTROL AUXILIARY STRUCTURE

#### Hydraulic Model Investigation

#### PART I: INTRODUCTION

#### The Prototype

- 1. The Old River Control Auxiliary Structure (Figure 1) is located within the lower limits of the Red River backwater area on the west bank of the Mississippi River about 48 miles\* northwest of Baton Rouge, Louisiana, and about 37 miles southwest of Natchez, Mississippi.
- 2. The approach channel to the structure has a bottom width of 500 ft, an invert elevation of -10.0,\*\* side slopes of 1 on 4 (Figure 2), and a length of approximately 2 miles from its junction with the Mississippi River. The approach training walls to the structure have a top elevation of 72.5 which is 3 ft above the crest of the project flood.
- 3. The structure is pile founded, constructed of reinforced concrete, and has a gross width of 442 ft between faces of abutment walls. The crest is surmounted by five 14-ft-wide piers that provide bays for six 62-ft-wide tainter gates (Figures 2 and 3). The gates are raised, lowered, and held in position by cables and drum hoists. The weir crest of the structure is set at an elevation of -5.0 to provide sufficient discharge for navigation and water supply needs with minimum stages in the Atchafalaya Basin.
- 4. The stilling basin (Figure 3) has a length of 210 ft, width of 442 ft, and floor elevation of -20.0. The stilling basin training walls with a top elevation of 55.0 terminate at the end sill. Energy dissipation is provided by two rows of 15-ft-high baffles and a 12-ft-high end sill with a face slope of 1V on 1H.
  - 5. The outlet channel is lined with riprap and has a trapezoidal cross

<sup>\*</sup> A table of factors for converting non-SI units of measurement to SI (metric) units is presented on page 3.

<sup>\*\*</sup> All elevations (el) and stages cited herein are in feet referred to the National Geodetic Vertical Datum (NGVD).

section with an inverted elevation of -10, a bottom width of 475 ft, and side slopes of 1V on 6H (Figure 2).

#### Purpose of Investigation

6. The model tests were conducted to determine the magnitudes, frequencies, and locations of the resultant hydrodynamic loads acting on the tainter gate's trunnions and hoist cables, and the stilling basin's apron monoliths, baffles, and end sill.

#### PART II: THE MODEL

#### Description

- 7. The section model was constructed to a linear scale of 1:50 and simulated one gate bay of 62 ft width (Figures 3 and 4). A 250-ft-long reach of the approach and exit channels was reproduced. The model sidewalls were constructed of plastic to permit visual observation of subsurface currents. As the study progressed, the simulated width of the stilling basin and exit channel was increased to 162 ft (Figure 2) to maintain water-surface profiles and hydraulic jump action indicated by the 1:50-scale model\* of the entire structure.
- 8. Water used in the operation of the section model was supplied by pumps, and discharges were measured by orifice meters. Water-surface elevations were measured by point gages.
- 9. The model gate was constructed of galvanized metal to simulate a prototype weight of 905 kips and the proper geometric configuration (Figure 5). The gate was supported by trunnions and a cable on each side of the gate. A spring was attached in each cable to simulate the elastic characteristics of the prototype cable. About 0.003 ft clearance was provided between each side of the gage and the model sidewalls to eliminate friction and excessive damping of forces. The hoist cables and trunnions were instrumented with strain gages to permit simultaneous measurement of the loads in the cables and the vertical and horizontal components of the resultant loads on the trunnions.
- 10. The stilling basin elements were constructed of machined aluminum and supported in the lateral horizontal plane by Teflon bearings mounted between the side of the stilling basin apron monolith and the model sidewalls to minimize friction (Figure 4). The stilling basin was supported in the vertical and longitudinal horizontal planes by rigid rods extending from the stilling basin to the strain gages (Figure 6). The rods were attached by pin connections at points A, B, and C (Figure 6). The strain gages had a maximum

<sup>\*</sup> Fletcher, B. P., and Bhramayana, P. "Old River Control Auxiliary Structure: Hydraulic Model Investigation" (in preparation), US Army Engineer Waterways Experiment Station, Vicksburg, Miss.

deflection of about 0.002 in. and were mounted to permit simultaneous measurement of the horizontal and vertical loads. About 0.004 ft clearance was provided between the four sides of the stilling basin to eliminate excessive friction and damping of forces.

#### Interpretation of Model Results

Il. The accepted equations of hydraulic similitude, based on the Froudian criteria, were used to express the mathematical relations between the dimensions and hydraulic quantities of the model and prototype. The general relations expressed in terms of the model scale or length ratio  $L_{\overline{r}}$  are presented in the following tabulation:

Dimension	Ratio	Scale Relation
Length	L <sub>r</sub>	1:50
Area	$A_r = L_r^2$	1:2,500
Velocity	$v_r = L_r^{1/2}$	1:7.07
Discharge	$Q_r = L_r^{5/2}$	1:17,678
Time	$T_{r} = L_{r}^{1/2}$	1:7.07
Force	$F_r = L_r^3$	1:125,000
Frequency	$F_{r} = 1/L_{r}^{1/2}$	1:0.14

12. Measurement of each of the dimensions or variables can be transferred quantitatively from model to prototype by means of the above scale relations.

#### PART III: TESTS AND RESULTS

#### System Response

13. Initial tests were conducted to determine the natural frequency and damping characteristics of the model components and instrumentation used to measure the dynamic forces. The natural frequencies of the model components, when submerged, are listed below:

Stilling basin apron monoliths

Type l (single monolith)

Vertical plane - 6 Hz

Horizontal plane - 26 Hz

Type 2 (monoliths 1 and 2)

Vertical plane - 24 Hz

Horizontal plane - 24 Hz

Tainter gate

Trunnions (vertical and horizontal planes) 100 Hz
Cables (with springs) - 14 Hz

The natural frequencies of the model components were considered too high to significantly influence either the magnitude or frequency of the hydraulic forces measured in subsequent tests which had a predominate frequency of about 0.2 Hz (prototype) or 1.4 Hz (model). Several tests conducted with and without the model submerged indicated no significant damping of the forces due to the mechanical system or the hydrostatic load.

#### Data Acquisition

14. The magnitude and frequency of forces acting on the gate trunnions, hoist cables, and stilling basin were simultaneously detected by strain gages and recorded on oscillograph charts. A typical oscillograph record is shown in Figure 7.

#### Forces Acting on Tainter Gate

15. Forces acting on the tainter gate (Figure 6) were measured for various gate openings and flow conditions. The various flow conditions

investigated are illustrated in Figure 8a-m. Flow conditions shown in Figures 8b and 8d are not anticipated to occur at the prototype structure but were investigated in the model to obtain results for a wide range of flow conditions. The forces detected on the tainter gates are tabulated in Table 1. Forces were consistent in tending to displace the trunnions in an upward and downstream direction as indicated by the force vectors in Figure 6. The trunnions were not subjected to a significant dynamic loading. Therefore, only a maximum trunnion loading condition is shown in Table 1. For example, Test 2 (Table 1) indicates that the left trunnion has an average force of 3,800 kips at an angle of 23 deg with the horizontal and the right trunnion has an average force of 3,700 kips acting at an angle of 26 deg and the hoist cables on each side of the tainter gate are subjected to an average load of 40 kips and a maximum force of 50 kips occurring at a rate of 0.2 Hz (prototype) in a downward direction. The hoist cables on both sides of each tainter gate are subjected to a downward force fluctuating from 30 to 50 kips at the rate of 0.2 Hz.

#### Forces Acting on Stilling Basin Elements

#### Type 1 monolith

16. The type 1 monolith consisted of a single slab extending from a point 6 ft downstream of the PI to the end sill and was supported in the model as shown in Figure 6. The resultant vertical and horizontal forces were determined by summing the vertical and then the horizontal loads at points A, B, and C (Figure 6). The location of the resultant force R was determined by summing moments about A (Figure 6) and solving for X.

$$X = \left[ \frac{R_{v} (22) / TAN\Theta + 180 (B_{v} + C_{v})}{R_{v}} \right] + 20$$

Resultant forces acting on the stilling basin are tabulated in Table 2. Flow conditions for Tests 1-18 are identical to those investigated in the tainter gate tests (Table 1). The underside of the stilling basin apron was subjected to a uniform hydrostatic load equivalent to the tailwater elevation. In most tests, due to the depressed water-surface profile of the hydraulic jump, the resultant stilling basin force was in an upward direction. However, some

tests were conducted with flow over the end sill near critical depth. This resulted in a higher water-surface elevation inside the stilling basin than the water surface downstream from the stilling basin, and the resultant force was in a downward direction. It should be noted that some values of X, tabulated in Table 2, denote the hydraulic resultant acting outside the stilling basin. The composite resultant would always act within the stilling basin due to the inclusion of the submerged stilling basin weight and sliding resistance. Stilling basin tests indicated that for all flow conditions the stilling basin was subjected to a significant dynamic force that occurred at about 0.2 Hz (prototype). For example, Test 2 (Table 2) indicates that an average shear force of 11.6 kips and a maximum shear force of 15.0 kips is acting on the stilling basin. The stilling basin is subjected to a minimum and maximum shear force of 8.2 to 15 kips at the rate of 0.2 Hz (see Figure 7).

- 17. Tests 20-26 were conducted with various elements in the basin removed as indicated by the sketches in Table 2. Results of Tests 20-26 provide limited guidance for estimating the hydraulic forces generated by various basin elements. The guidance is limited due to the change in the hydraulic jump after the baffles and/or end sill are removed. Efforts to keep from altering the jump were successful as described in paragraph 20.
- Type 2 monoliths
- 18. Following tests of the type I monolith, New Orleans District engineers decided that the stilling basin apron would be composed of two monoliths due to the length of the apron involved. The model was revised to simulate two monoliths and permit simultaneous measurement of the forces acting on the two independent monoliths (Figure 9). The model facility was also modified by widening the flume downstream from the downstream end of the piers from a width of 62 ft to a width of 162 ft to permit simulation of low tailwater elevations and flow expansion that occurs with single gate operation. Simulation of multiple gate operation required the capability of reducing the flume width to 62 ft by use of a removable divider wall (Figure 2). Details of the mounting system and notations relative to the resultant forces are shown in Figure 9. The procedure for data analysis is similar to that described in paragraph 16.
- 19. Resultant forces acting on each monolith are tabulated in Table 3. The location of the resultant force,  $R_1$  (monolith 1) was determined by

summing moments about A and solving for X, (Figure 9).

$$X_1 = \left[ \frac{R_v (23) / TAN\Theta + 55 (B_v + C_v)}{R_v} \right] + 12.5$$

The location of the resultant force,  $R_2$  (monolith 2) was obtained by summing moments about D and solving for  $X_2$ .

$$X_2 = \left[\frac{R_v (23)/TANO + 55 (E_v + F_v)}{R_v}\right] + 12.5$$

20. Tests were conducted to measure the individual and collective hydraulic drag and uplift forces acting on the baffles, end sill, and type 2 monoliths. Initially, the end sill was detached but positioned a distance of 0.25 ft (prototype) above the monolith (Figure 10) in order to maintain the hydraulic flow conditions. This permitted measurement of the collective drag and uplift forces acting on the second row of baffle piers and the stilling basin apron. The resultant forces acting on monolith 2 with the end sill detached are tabulated in Table 4. The baffles were detached from the apron monoliths and supported at a distance of 0.25 ft above the monoliths (Figure 11). This enabled measurement of the drag and uplift forces acting on each apron monolith without the influence of forces that are imposed on the baffles. Forces acting on monoliths 1 and 2 with the baffles detached are tabulated in Table 5. The drag and uplift forces due to the end sill can be obtained by subtracting values obtained with the end sill detached (Table 4) from values obtained with the end sill attached (Table 3). The drag and uplift forces due to the first row of baffles (monolith 1) can be obtained by subtracting values in Table 5 from values obtained with the baffles and end sill attached (Table 3). The drag and uplift forces due to the second row of baffles (monolith 2) can be obtained by subtracting values in Table 5 from values in Table 3. The drag and uplift forces acting on the apron of monolith I are tabulated in Table 5. The drag and uplift forces due to the apron of monolith 2 can be obtained by subtracting the sum of the respective values for the second row of baffles and end sill from the values in Table 3. The individual and collective drag and uplift forces acting on the baffles, end sill, and the type 2 monolith aprons are tabulated in Table 6.

21. Piezometer and electronic pressure cells were located level with the surface of the stilling basin and in the baffles and end sill as shown in Figure 12 to measure the magnitudes of the average and instantaneous pressure fluctuations. Values obtained for various flow conditions are tabulated in Table 7.

#### Water-Surface Profiles

- 22. Water-surface profiles obtained for various flow conditions are shown in Figure 13 with basic data defining the profiles also included.
- 23. A comparison of the water-surface profiles (Figure 13) with the pressures detected by the piezometers (Table 7) indicates, at some locations, a considerable difference in pressure and equivalent depth for identical flow conditions. The water-surface profile indicates the depth of water relative to the surface of the stilling basin whereas the piezometers indicate a point pressure relative to the surface of the stilling basin that is significantly affected by air entrainment and localized turbulence and flow direction. Depending on its location in the stilling basin, a piezometer could indicate an average pressure higher or lower than the equivalent depth of water over the sensor.

#### Debris on Tainter Gate

24. Although only limited accumulations of debris are expected, tests to evaluate debris passage during gate flows were conducted with debris that varied in size from 12 ft long and 0.75 ft in diameter to 50 ft long and 5 ft in diameter. Tests indicated that debris would pass underneath the gate and remain in the back roller on the downstream side of the gate. The debris did not impart severe loads to the tainter gate but tended to collect on the downstream side of the gate in the girders and strut arms (Figure 14, type 1 gate). The debris was considered a potential problem in raising and lowering the gate. The problem was alleviated by covering the strut arms and girders with a skin plate which prevented the accumulation of debris. A skin plate was also added immediately downstream from the gate 1ip (Figure 14, type 2 gate) to prevent accumulation of debris that might prevent proper closing of the gate.

25. The addition of the skin plates did not affect the hydraulic forces on the tainter gate.

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#### PART IV: SUMMARY AND DISCUSSION OF RESULTS

- 26. Results of tests conducted with the stilling basin apron monoliths and tainter gate immersed in water indicated that the natural frequency of the model was too high to influence the results of the tests and there was no discernible damping of the forces due to the mechanical system.
- 27. Force measurements at the gate trunnions indicated that the trunnions were subjected to static loadings that tended to displace the trunnions in an upward and downward direction.
- 28. The model gate hoist cables were designed to simulate the proposed prototype cable characteristics. Hoist cable hydraulic loads were always in a downward direction. Some flow conditions produced a periodic loading (in the hoist cables located on each side of the gate) that occurred at an amplitude of 20 kips and a frequency of 0.2 Hz.
- 29. Tests were conducted to determine the location, direction, and frequency of the resultant forces acting on the stilling basin apron monoliths and to measure the individual and collective hydraulic drag and uplift forces acting on the baffles, end sill, and stilling basin apron monoliths. The upstream independent monolith was surmounted by a row of baffle blocks and the downstream independent monolith was surmounted by a row of baffle blocks and end sill. The individual drag and uplift forces acting on the aprons, baffles, and end sill were determined by conducting tests with the baffles and then the end sill detached but positioned a distance of 0.25 ft (prototype) from the apron to preserve the characteristics of the hydraulic jump.
- 30. The measured drag forces on the baffle blocks was significantly higher than drag forces computed from the drag coefficient in EM 1110-2-1603\*. This indicates the need for research or site-specific studies to develop design guidance for determining the individual and collective forces acting on stilling basins.
- 31. Piezometers and electronic pressure cells were used to measure pressure distribution in the stilling basin. Water-surface profiles were obtained along the longitudinal center line of the stilling basin.
  - 32. Tests conducted to evaluate debris passage through the tainter

<sup>\*</sup> Headquarters, Department of the Army. 1965 (Mar). "Hydraulic Design of Spillways," Engineer Manual EM 1110-2-1603, Washington, DC.

gates indicated a tendency for debris to accumulate on the downstream side of the gate. Debris accumulation was eliminated by covering the girders on the downstream side of the gate with a skin plate. The skin plate did not alter the hydraulic loads on the tainter gate.

Table 1

Magnitude, Frequency, and Direction of Resultant Average and Maximum Hydraulic Forces Acting on Tainter Gate

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No significant periodic forces acting on trunnions; therefore, maximum force is a static (average) condition. Tabulated values do not include weight of tainter gate. Direction of horizontal and vertical forces indicated by arrows (\*). All values are listed in prototype equivalents. Note:

\* See Figure 7.

Table ?

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Type I Monolith Design; Magnitude, Frequency, Location, and Direction of Resultant Average and Maximum Hydraulic Forces Acting on Stilling Basin per Foot of Basin Width

		Design		_	_	_				_				_			_		_		-		-	. •	+			-
		Flow Conditions	Submerged controlled flow	Submerged controlled flow	Free controlled flow	Submerged controlled flow	_		-							_			•	-	Submerged uncontrolled flow	Submerged controlled flow						merged uncontrolled flow
	Frequency (f)	cpe	0.2	•		_			_	_						-				_				_	_		<u></u>	•
sin Width	Resultant Angle	deg	23.8	59.0	35.0	27.6	68.7	64.3	59.3	51.0	21.8	63.2	6.0	28.8	52.0	57.8	58.4	54.9	45.0	42.9	31.4	69.7	70.0	75.0	73.4	86.1	97.6	46.2
Maximum Force Per Foot of Stilling Basin Width	Resultant Location (X)	٤	155.0	0.09	165.2	88.0	115.9	75.0	8.09	123.6	-38.1	72.0	-112.7	150.6	111	126	108	139	105	130	38	66.1	50.2	55.1	56.3	78.0	0.89	125
r Foot of	Resul- tant (R)	419	14.9	29.0	8.6	20.0	14.6	37.6	32.5	13.7	5.9	21.7	13.5	22.8	25.7	11.5	13.8	6.6	0.42	23.1	26.1	35.9	26.0	40.1	27.7	36.5	28.5	23.3
Force Per	Horizon- tal (R <sub>H</sub> )	k1p	13.6+	15.0+	8.0+	17.8+	5.3•	16.3+	16.6+	8.6+	5.5+	9.8	13.4+	20.0+	15.8+	<b>€.</b> I÷	+6.4	5.7•	0.3+	16.9	22.3+	11.7•	8.9	10.4+	7.9•	1.2+	1.2+	16.1+
Maximum	Verti-	T I	6.04	25.0	5.6	9.3+	13.6+	33.9+	27.9+	10.64	2.24	19.41	1.4.1	11.0	20.24	9.7+	12.9+	8.1.	0.3	15.7+	13.64	31.64	24.4+	38,74	26.5+	36.5+	28.5+	16.8
in Width	Resul- tant Angle	qe	0.4	59.6	59.9	9.1	72.7	60.7	60.5	50.7	54.0	63.3	33.0	11.4	50.6	60.3	69.7	53.7	;	37.7	0.84	70.0	70.0	76.6	75.3	0	0	42.0
Foot of Stilling Basin Width	Resultant Location (X)	=	6,135	43	144	1,055	113.9	42.5	60.5	118.5	1.65	69.7	28.6	202.7	117.3	132	101	135	:	126	66.3	45.9	63.9	7.87	50.2	73.3	75.1	132
Foot of	Resul- tant (R)	k f P	0.6	23.0	11.0	12.2	10.8	25.8	25.6	10.0	5.4	15.4	9.5	14.7	16.7	8.1	10.7	9.9	0	17.7	27.3	26.4	19.6	٥. ۲	0.5	31.6	21.8	17.8
Iverage Force Per	Herizon- tal (R <sub>H</sub> )	k îp	• U· 6	11.6-	5.5	12.1+	3.2.	12.7	12.6+	6.3-	3.2.	6.9	8.0.	14.4.	10.6+	4.0+	3.7•	3.9.	င	14.0+	18.3	•0.6	9.9	7.4.	5.2.	c	0	13.2•
Average	Verti- cal	k P	0.164	19.81	9.5		10.3	22.6+	22.3*	7.7	4.4.	13.7	5.2'	2.9	12.9.	7.0	10.01	5.34	O	10.8	20.3	24.8.	18.5	31.1	19.8	31.6	21.8+	11.9.
	₹	=1	2,0	۴3	-	-	æ	84	35	÷	٧		¢	2	16	:3	<u>-</u>	۲	23	13	22	43	17	۲3	17	43	<u>:</u>	ζ,
1	Tail-	=	æ	9:	¢	51	.,	17	<u>~</u>	53	:	35	35	<u>0</u> :	53	97	38	Š	95	34	9	36	35	3,6	35	5.6	35	30
1	Head-	ţ	ķ	9	2	47	4	:	5.4	04	œ	55	7	5.	64	64	Ų.	4	69	Ş	Ş	64	5.2	69	\$2	64	52	5.5
	Cate Oper- ink	٤	٠.	,	10	اں	c.		=	=	<u> </u>	51	٤.	35	۲,	• •	12.4	41	c. -	34.0	Fu! 1v	٧.	15	7.5	13	۲.		Fullv
	Unit Dis- charge	cfs'ft	270	υlί	2.0	υ·•		0. 7										285										1,170
1	Test	ž	٠.	٠.	~	-1	v	ı		ar.	σ	U1	Ξ	-	-	7.	<u> </u>	91	-	18	0.	Š	2.1	84	23	; ;	ř.	ζ,

Note: Tabulated values do not include veight of stilling basin. Direction of horizontal and vertical forces indicated by arrows (+). All values are listed in prototype equivalents. Underside of stilling basin subjected to a uniform hydrostatic load equivalent to 100 percent tailwater.

Table 3

Type 2 Monolith Design; Magnitude, Frequency, Location, and Direction of Resultant Average and Maximum Hydraulic Forces Acting on Stilling Basin per Foot of Basin Width

					1		1000	Ream								
				Vert1-	Horizon-	Resul-	Resultant	tant	Verti-	Horizon-	Resul-	Resultant	Resultant			
•	-11e			Cal	[ a)	tant	Location	Angle	cal	( 0 )	tant	Location	Angle	Frequency		
-	ater		Η,	( <del>R</del>	Ŧ,	£	£	ပ	(H)	È.	( <u>R</u>	£	ij	Ξ		
11 11	٤		إد	k io	k1p	k 1p	fr	deg	k1v	k1p	k1p	fr	deg	cps	Flow Conditions	De s 1gn
								Mono11	Monolith Number	-1						
	24.	_	27.7	7.01	11.11	11.8	22.5	19.8	þ	14.0+	14.0	8	0	0.2	Free uncontrolled flow	
59.0 53.0	53.	0	16.0	4.5+	4.2+	6.2	63.3	47.0	7.14	5.8+	10.1	54.0	51.4	0.2	Submerged controlled flow	
	39.	c	16.0	0	7.8•	7.8	8	0	5.5+	11.00	11.7	82.0	26.6	0.2	Submerged controlled flow	
	45		24.0	4.6	3.4+	5.7	45.0	53.5	6.04	5.0	7.8	76.5	50.2	0.2	Submerged controlled flow	
52.0 35	35	0.	17.0	4,4	4.7.	9.6	42.6	8.09	13.9+	6.3+	15.3	0.74	6.49	0.2	Submerged controlled flow	
								Monoli	Monolith Number 2	7]						
	7,	۲.	27.7	10.3	10.6+	14.8		44.2	15.2+	14.5+	21.0	45.2	7.67	0.2	Free uncontrolled flow	
-	53	0	16.0	2.9+	1.8.	3.4		58.2	4.2+	3.7+	5.6	53.7	9.87	0.2	Submerged controlled flow	
55.0 39	39	٥.	16.0	1.9+	4.4.	8.4	73	23.4	4.7+	6.5	8.0	72.0	35.9	0.2	Submerged controlled flow	
-	45	45.1	24.0	1.81	0.5+	1.9		74.5	3.4+	1.4.	3.7	31.4	67.6	0.2	Submerged controlled flow	
•	3	0	0.7	17.7	.8	7.7		56.3	+6.4	47 8	0.9	55.0	55.2	0.2	Submerged controlled flow	

Note: Tabulated values do not include weight of stilling basin. Direction of horizontal and vertical forces indicated by arrows (+). All values are listed in prototype equivalents. Underside of stilling basin subjected to a uniform hydrostatic load equivalent to 100 percent tallwater.

Table 4

Type ? Honolith Design; End Sill Detached From Monolith Number 2; Magnitude,

Frequency, Location, and Direction of Resultant Average and Maximum Hydraulic Forces Acting on Stilling Basin per Foot of Basin Width, Monolith Number 2

	Design		:	•	:	:
	Flow Conditions	Free uncontrolled flow	Submerged controlled flow	Submerged controlled flow	Submerged controlled flow	Submerged controlled flow
	Frequency (f) cps	0.2	0.2	0.2	0.2	0.2
asin Wideh	Resultant Angle O deg	42.6	9.07	27.4	67.7	58.0
Maximum Force Per Foot of Stilling Basin Wide	Resultant Location (X) ft	37.5	20.5	26.0	22.0	76.4
Foot of	Resultant (R)	11.7	3.9	3.3	2.4	2.8
Force Per	Horizon- cal (R <sub>H</sub> ) kip	\$.	ቷ.	2.3	<b>\$</b> .0	<u>ታ</u>
Maximum	verti- cal (R) kip	7.9+	3.74	1.5+	2.2+	2.44
Width	Resultant Angle G deg	53.8	71.5	0	76.0	52.4
Average Force Per Foot of Stilling Basin W	Resultant Location (X) ft	29.0	20.2	8	19.2	30.2
ot of St	Resultant (R)	7.4	2.5	1.8	1.7	1.6
rce Per Fo	Horizon- tal (R <sub>H</sub> )	4.4.	9.0	æ: -	0.4.	<u>.</u>
erage Fo	Vert t- cal (R) ktp	6.0	2.4+	0.0	1.6+	1.3
¥	٠. ع		٥.4	16.0	24.0	11.0
	Tail- vater ft	24.3	53.0	39.0	45.1	35.0
	Head-	52.0	0.69	55.0	1.69	\$2.0
	Cate Open- ing	Fullv	=	35.0	,† •	<u>.</u>
	Unit Dis- charge cfs/ft	1,370	280	950	111	007
	les C	32	33	34	35	36

Note: Tabulated values do not include weight of stilling basin. Direction of horizontal and vertical forces indicated by arrows (+). All values are listed in prototype equivalents. Underside of stilling basin subjected to a uniform hydrogratic load equivalent to 100 percent tailwater.

Table 5

Type 2 Monolith Design; Each Row of Baffles Detached from Monoliths; Magnitude, Frequency, Location, and Direction of Resultant Average and Maximum Hydraulic Forces

Acting on Stilling Basin per Foot of Basin Width

					Design				:	=	=	=		=	=	=	=	:
					Flow Conditions			Free uncontrolled flow	Submerged controlled flow	Submerged controlled flow	Submerged controlled flow	Submerged controlled flow		Free uncontrolled flow	Submerged controlled flow	Submerged controlled flow	Submerged controlled flow	Submerged controlled flow
			requency	£	cps			0.2	0.3	0.2	0.2	0.2		0.2	0.2	0.2	0.3	0.2
asin Width		Resultant	Angle	ن	deg			86.9	83.3	17.1	6.61	9.78		52.6	77.3	4.6	74.0	37.4
Maximum Force Per Foot of Stilling Basin Width		Kesuitant	Location	£	٢			33.2	36.1	48.3	50.0	46.5		9.09	74.0	33.0	62.5	76.8
Foot of			t and		k1p			11.1	3.4	3.6	5.9	5.3		12.8	3.2	3.7	2.2	2.1
Force Per	Hor1zon-		(8)	Œ.	k1p	-	-1	0.6+	4.4.0	0.8	0.5+	0.5+	~]	7.8+	0.7+	3.7+	9.0	1.7
Maximum	:	Vert 1-	c.e.]	<u>.</u>	2	7 W. H.	HOHOTTEN NUMBER	11.1+	3.4+	3.5	2.8+	5.3+	Monolith Number	10.24	3.1+	0.34	2.14	1.3+
Ι.							4 I											
Width	Resul-	tant	Angle	0	deg	Monoli		06	90	90	96	9	Mono 1,1	40.7	82.6	35.3	81.9	37.6
liing Basin Width					ı	Lonox	TOHOL	43.0	25.1 90		30.5		Monoli	49.0 40.7				69.0 37.6
ot of Stilling Basin Width		- Kesultant	tant Location Angle		ı	Conce	TOLION	16.3 43.0 90		1 53.3	30.5	26.8	Monoli	8.4 49.0 40.7		67.0	53.0	
ce Per Foot of Stilling Basin Width		Kesul- Kesultant	tant Location	(R) (X)	ı		TOHOL	16.3	2.1	6.1 53.3	30.5	3.1 26.8	Monoli	7.8	2.3 64.0	2.9 67.0	1.4 53.0	0.69
100	Horizon-	tal Kesul- Kesultant	(R) tent Location	(K) (X)	k1p fr		TOLOR	0 16.3	0 2.1	0 6.1 53.3	1.6 30.5	0 3.1 26.8	Hono11	7 7 8 4 9 9 7	0.3+ 2.3 64.0	2.4+ 2.9 67.0	0.2+ 1.4 53.0	0.69 8.0
Average Force Per Foot of Stilling Basin Width	Horizon-	tal Kesul- Kesultant	cal (R) tant Location	(R) (R) (X)	kip kip fr		TOHOU	16.34 0 16.3	2.1 0 2.1	6.11 0 6.1 53.3	0 1.6 30.5	3.1+ 0 3.1 26.8	Mono)1	5.5+ 6.4+ 8.4	2.3+ 0.3+ 2.3 64.0	1.7 2.4 2.9 67.0	1.4+ 0.2+ 1.4 53.0	0.64 0.8 69.0
100	Horizon-	Verti- tal Kesul- Kesultant	Tail- cal (R) tant Location	water (H (R) (R) (X)	ft ft kip kip kip ft		TOHOL	27.7 16.34 0 16.3	16.0 2.1 0 2.1	16.0 6.11 0 6.1 53.3	1.6+ 0 1.6 30.5	17.0 3.1+ 0 3.1 26.8	Monoli	27.7 5.5+ 6.4+ 8.4	16.0 2.3+ 0.3+ 2.3 64.0	16.0 1.74 2.4+ 2.9 67.0	24.0 1.4+ 0.2+ 1.4 53.0	0.54 0.6+ 0.8 69.0
100	Horizon-	Verti- tal Kesul- Kesultant	Tail- cal (R) tant Location	water (H (R) (R) (X)	fr kip kip fr		TOHOL	24.3 27.7 16.34 0 16.3	53.0 16.0 2.1+ 0 2.1	39.0 16.0 6.14 0 6.1 53.3	24.0 1.6+ 0 1.6 30.5	35.0 17.0 3.1+ 0 3.1 26.8	Monoli	24.3 27.7 5.5+ 6.4+ 8.4	53.0 16.0 2.3+ 0.3+ 2.3 64.0	39.0 16.0 1.7+ 2.4+ 2.9 67.0	45.1 24.0 1.4+ 0.2+ 1.4 53.0	17.0 0.5+ 0.6+ 0.8 69.0
100	Horizon	Verti- tal Kesul- Kesultant	Head- Tail- cal (R) tant Location	water water (M.) (M.) (M.)	ft ft kip kip kip ft		TOUGH TOUGHT	Fully 52.0 24.3 27.7 16.34 0 16.3	11 69.0 53.0 16.0 2.1+ 0 2.1	35 55.0 39.0 16.0 6.14 0 6.1 53.3	6.4 69.1 45.1 24.0 1.6+ 0 1.6 30.5	15 52.0 35.0 17.0 3.1 0 3.1 26.8	Honoli	7 52.0 24.3 27.7 5.5+ 6.4+ 8.4	69.0 53.0 16.0 2.3+ 0.3+ 2.3 64.0	55.0 39.0 16.0 1.74 2.4+ 2.9 67.0	69.1 45.1 24.0 1.4+ 0.2+ 1.4 53.0	35.0 17.0 0.5+ 0.6+ 0.8 69.0
100	Hortzon	Cate Verti tal Resultant	Open- Head- Tail- cal (R) tant Location	ing water water (H (R) (H) (X)	fr ft ft kip kip ft		TOLOGI	Fully 52.0 24.3 27.7 16.34 0 16.3	11 69.0 53.0 16.0 2.1+ 0 2.1	35 55.0 39.0 16.0 6.14 0 6.1 53.3	69.1 45.1 24.0 1.6+ 0 1.6 30.5	15 52.0 35.0 17.0 3.1 0 3.1 26.8	Monoll	Fully 52.0 24.3 27.7 5.5+ 6.4+ 8.4	11 69.0 53.0 16.0 2.3+ 0.3+ 2.3 64.0	35 55.0 39.0 16.0 1.74 2.4+ 2.9 67.0	6.4 69.1 45.1 24.0 1.4+ 0.2+ 1.4 53.0	52.0 35.0 17.0 0.5+ 0.6+ 0.8 69.0

Note: Tabulated values do not include weight of stilling basin. Direction of horizontal and vertical forces indicated by arrows (+). All values are listed in prototype equivalents. Underside of stilling basin subjected to a uniform hydrostatic load equivalent to 100 percent tailwater.

Podrant, o Forces Atting or Individual and combined Stilling basin temeries

Type 2 Monolith Design Dynamic Forces

÷6	٦	E E		14.0 >	5.8	11.0	2.0.4	6.54		1	11	Max	14.53	3.7 >	6.5-9	1.4 >	3.4.3
Baffles and Aprons,** kips	Drag/	80		.1.11	4.2.4	7.8 >	3.4.	6.7.3		,	Drag/ft	A v 8	10.64	48.2	4.4	. 5.0	1.83
affles and A	plift/it	×		 C	7.14	5.5+	6.0.	13.9•		1100 600	ft/ft	Max	15.27	4.24	4.71	3.47	4.97
æ		ا ا		70.5	4.5+	0.0	. 6.	• 7.8		. ( ) . 0	Uplift/	Ave	10.31	2.94			2.75
		× i		0.4.0	0.4.	. R. C	0.5.	0.5•		į	Drag/ft	Avg Max	0.2-	0.24 0.64	24 0.19	1. O. H	2, 0.0
1 IPs	Drag'it	AV AV		Ξ	٥	c	ε	c		***	1001	fax. Av	97 0.	.6 0.	.44.	.4,	.24 0.
Apron, ** kips	-	<b>∢</b> I								,	P11: t/ft	IVE Ha	.23 2.	.81 2.	. <u>.</u>		?₄ 1.
	111111	X as K		; :-	3.44	3.54	2.4	5.3			-	Hax Av	.4, 1.	.1 49.1	.6- 2.	3.5, 1.	.9. 1.
		N/N/N/N/N/N/N/N/N/N/N/N/N/N/N/N/N/N/N/		14.	2.1+	÷1.9	1.6.				Drag/ft	Avg	6.21	0,54	2.67 3	_	_
	Baffle	X S	Samber 1	3.75		2014	·	153.	Number		/ft Drag	A.	7.30	0.5+	1.7.	0.7•	2.5.
* ktps	Drag Baffle	W.B	Monolite	277.	.48	160	÷02	• 46	Monolith Number		Uplift/ft	AvB	4.3	0.5+	0.4+	0.2+	1.44
Hatiles, * kips	١.	×			16.	185.	14+	176.			Drag/Baffle	X X	506+	14.	4		
Í	Plitt Baffle									:	Drag/	AVR	136.	. 47	·	÷	17.
	[편]	× ×		.5.	• 67	125	624	108		;	Uplift/Baffle Drag/Baff	Max	154.	7	135+	· U,7	
Horizon- tal	_ تخر	11			16.0	0.91	24.0	0.71			Uplift	Av.	148.	.8~	-111	÷ ; ;	* ** **
Tail-	Cater	=			53.0	39.0	45.1	35.0		Horizon- tal	<u>_</u>	ktp	27.7	0.91	16.0	24.0	17.0
-		اب		с.	o.	٥.	-	52.0		;	- IBI	1	24.3	53.0	39.0	45.1	35.0
Hea	water	-		5.3	69	5.5	69	52		:	Head-	۳	52.0	0.69	55.0	1.69	52.0
Cate Open-	tux.	=		Fu115	-:	35	9	2		Cate	npen-	#	Fully	11	3.5	. <del>,</del> ,.0	5
Unit Dis-	harge	cts) tr		1.1	280	056	:	005		Untr	pisc	cfs/tt	1.370	280	950		707

Tabulated values do not include weight of stilling basin. Direction of horizontal and vertical forces indicated by arrows (·). All values are listed in prototype equivalents. Underside of stilling basin subjected to a uniform hydrostatic load equivalent to 100 percent tailwater. Maximum forces occur at a frequency of 0.2 cycles ner second (prototype).

Forces acting to baffles are tabulated as force per baffle (each haffle is 9.8) ft wide).

Forces acting on aprons, end sill, combined apron and baffles on apron, baffles, and end sill are tabulated as a unit force per foot of monolith width (monolith and end sill width in model = 61.5 ft). Note:

Table 7	Pressures in Old River Control Auxiliary Structure	Stilling Basin Monoliths (Type 2)
---------	--	-----------------------------------

		Pressu	Pressure Per Foot of H <sub>2</sub> 0	0	
	Test No. 27	Test No. 28	Test No. 29	Test No. 30	Test No. 31
	$G_0 = Full$	$G_0 = 11$ ft	$G_0 = 35$ ft	$G_0 = 6.4 \text{ ft}$	$c_0 = 15$ ft
	q = 1,370  cfs/ft	q = 280 cfs/ft	q = 950  cfs/ft	q = 177 cfs/ft	q = 400  cfs/ft
Piezometer	H = 52.0 ft	H = 69.0 ft	H = 55.0 ft	H = 69.1 ft	H = 52.0 ft
No. Elevation		h = 53.0 ft	h = 39.0 ft	h = 45.1 ft	h = 35.0 ft
1 -20.0		56.0	43.0	45.0	37.0
		55.0	43.0	45.0	35.0
٣	31.5	54.0	42.0	0.44	34.0
7	29.5	53.0	41.0	0.44	34.0
2**	3.5	3.0	3.0	3.0	3.0
9	28.0	53.0	40.0	45.0	34.0
7	28.6	53.0	41.0	45.0	34.0
80	29.5	53.0	41.0	45.0	34.0
6	*	*	*	*	*
10	*	*	*	*	*
11	31.0	53.0	0.14	45.0	35.0
1.2	*	*	*	*	*
13	36.0	55.0	45.0	45.0	36.0
14	39.0	26.0	47.0	47.0	38.0
15** ▼	6.5	4.0	0.4	3.0	5.0
16 -7.5	49.0	0.09	54.0	78.0	0.04
	51.0	0.49	55.0	52.0	45.0
18 -17.5	49.5	63.0	53.0	53.0	45.0
	*	*	*	*	*
20	22.0	53.0	39.0	45.0	35.0
21	23.5	53.0	40.0	45.0	35.0
22	25.5	53.0	40.0	45.0	35.0
23	26.0	53.0	40.0	45.0	36.0
24	26.5	54.0	41.0	0.94	36.0
25	27.0	54.0	41.0	0.94	36.0
		,			

Piezometer locations are shown in Figure 12. Elevations are in feet.
Piezometer malfunction.
Electronic pressure cells - amplitude of maximum pressure fluctuation in feet. Note:

(Continued)

(Sheet 1 of 3)

Plezometer No. Elevation 26	Test No. 27	Test No 28		Test No. 30	Test No. 31
Piezometer	Gn = Full	. ~	$G_0 = 35 \text{ ft}$	G = 6.4 ft	44
Piezometer o. Elevati	370 c	σ.	q = 950  cfs/ft	77 cf	q = 400 cfs/ft
	H = 52.0  ft h = 24.3  ft	H = 69.0  ft h = 53.0  ft	H = 55.0 ft h = 39.0 ft	H = 69.1  ft $h = 45.1  ft$	H = 52.0  ft $h = 35.0  ft$
-	27.0	53.0		45.0	36.0
1	28.0	53.0	41.0	45.0	37.0
28	28.0	53.0	0.04	0.94	37.0
6	29.0	54.0	0.04	0.95	37.0
30**	3.5	1.5	1.5	1.5	1.5
31	29.0	54.0	41.0	0.94	37.0
32 -8.0	19.0	54.0	38.0	0.94	36.0
33 -20.0	37.5	53.0	45.0	0.94	39.0
	26.0	51.0	39.0	0.44	33.0
	16.5	47.0	35.0	41.0	30.0
90	19.0	50.0	36.0	43.0	32.0
37	23.0	51.0	38.0	0.44	33.0
<b>►</b>	26.0	53.0	39.0	45.0	34.0
39 -19.0	26.0	53.0	35.0	78.0	37.0
40 -15.0	25.0	52.0	36.0	0.95	33.0
	25.0	54.0	37.0	46.0	34.0
42 -5.0	25.0	54.0	38.0	45.0	33.0
	24.0	53.0	38.0	45.0	33.0
14 -5.0	23.0	53.0	38.0	45.0	33.0
	23.0	53.0	37.0	0.44	34.0
46 15.0	23.0	53.0	38.0	0.44	34.0
	*	53.0	38.0	0.44	34.0
48 25.0	*	53.0	38.0	0.44	34.0
30.0	*	52.0	38.0	0.44	*
	*	52.0	37.0	0.44	*
	*	53.0	*	*	*
	*	*	*	*	*
53 50.0	*	*	*	*	*
	29.5	54.0	42.0	45.0	35.0

\* Piezometer malfunction. \*\* Electronic pressure cells - amplitude of maximum pressure fluctuation in feet.

(Continued)

(Sheet 2 of 3)

Table 7 (Concluded)

	Test No. 27	Test No. 28	Test No. 29	Test No. 30	1
	G = Full	C <sub>0</sub> = 11 ft	$G_0 = 35 \text{ ft}$	$G_0 = 6.4 \text{ ft}$	
	q = 1,370 cfs/ft	q = 280 cfs/ft	q = 950 cfs/ft	q = 177 cfs/ft	
Plezometer	H = 52.0 ft	H = 69.0 ft	H = 55.0 ft	H = 69.1 ft	
No. Elevation	h = 24.3 ft	h = 53.0 ft	h = 39.0 ft	h = 45.1 ft	h = 35.0 ft
	27.0	53.0	40.0	45.0	34.0
56 -10.0	25.0	53.0	38.0	45.0	34.0
	24.0	53.0	39.0	45.0	34.0
58 0	24.0	52.0	38.0	45.0	34.0
	23.0	52.0	39.0	0.44	34.0
0.01 0.0	23.0	53.0	38.0	0.44	34.0
	*	53.0	38.0	0.44	34.0
	*	53.0	38.0	0.44	35.0
	*	53.0	38.0	0.44	34.0
64 30.0	*	53.0	38.0	0.44	*
	*	53.0	*	*	*
	*	*	*	*	*
67 45.0	*	*	*	*	*
	*	*	*	*	*

\* Piezometer malfunction.

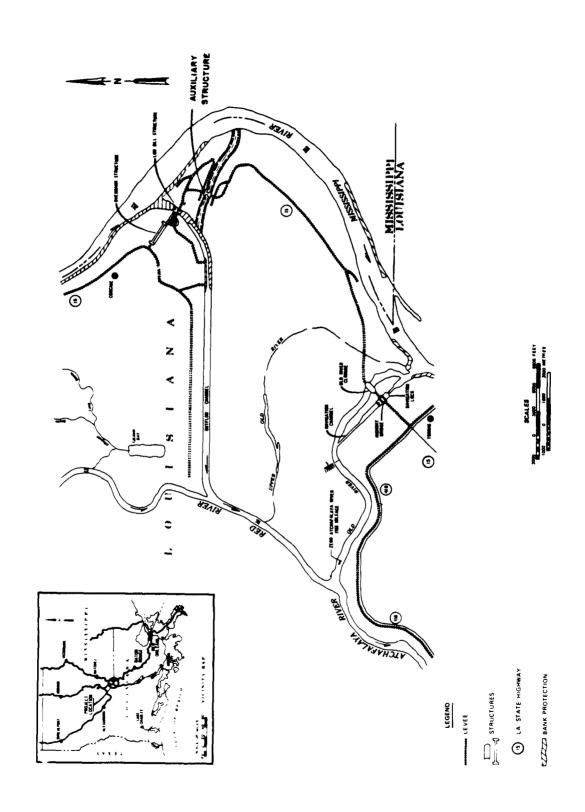
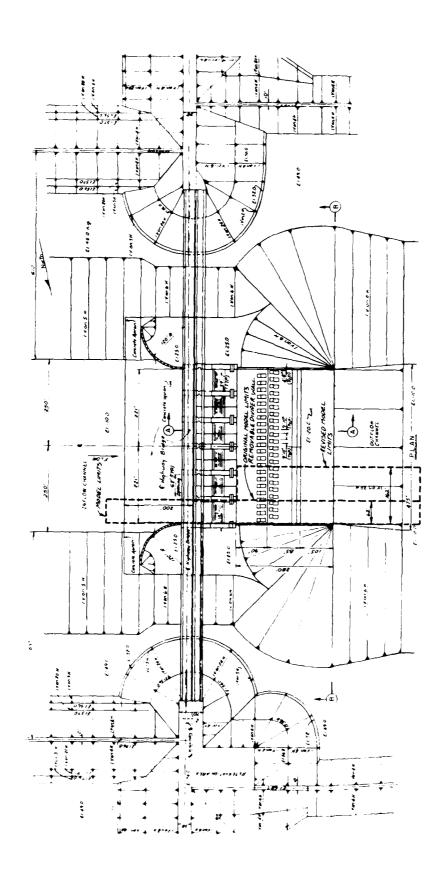


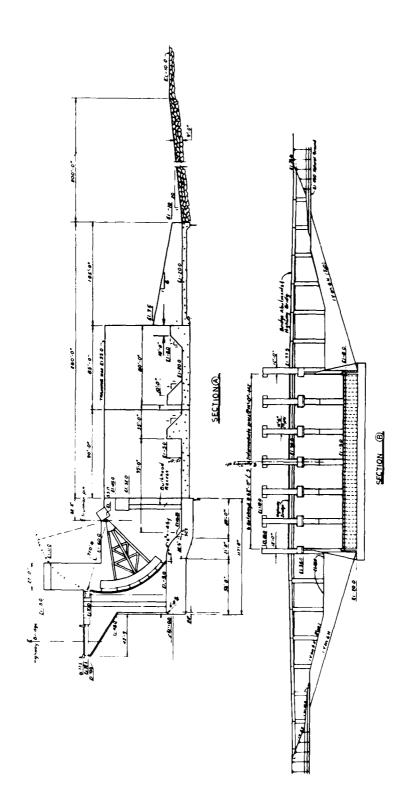
Figure 1. Vicinity map



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Figure 2. Plan view

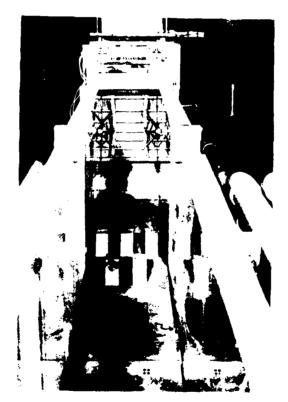


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Figure 3. Section model of stilling basin



a. General view



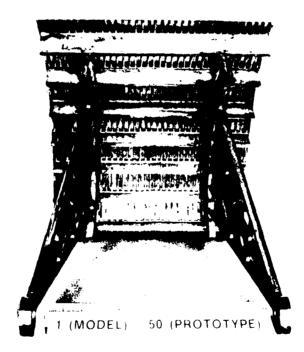
b. Viewed from downstream

Figure 4. 1:50-scale section model



1 (MODEL) 50 (PROTOTYPE

a. Viewed from side



b. Viewed from downstreamFigure 5. Tainter gate

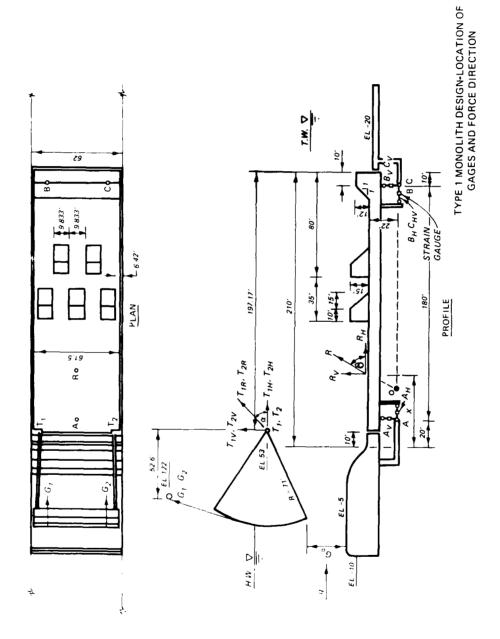


Figure 6. Stilling basin

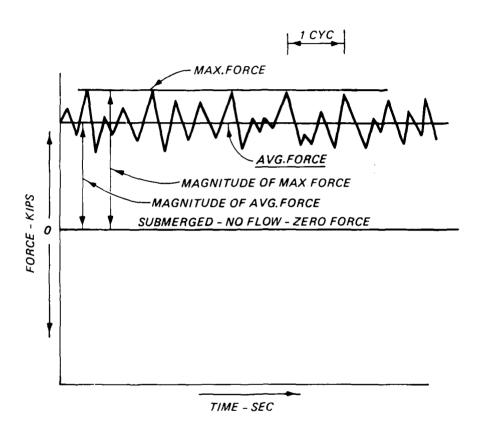
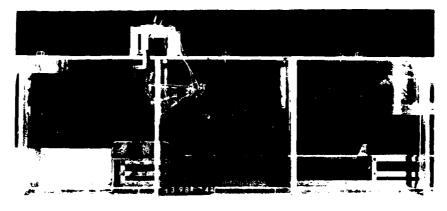


Figure 7. Typical oscillograph record for stilling basin





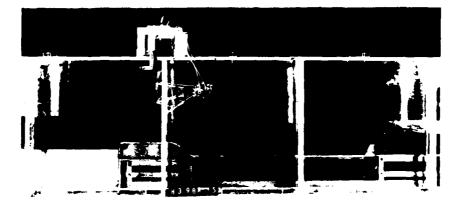
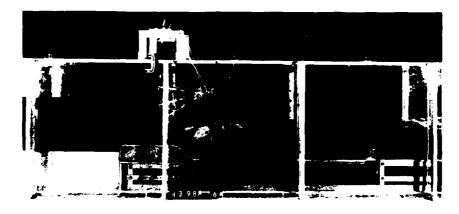
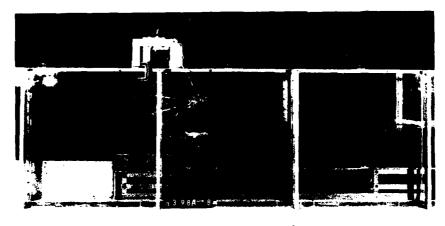


Figure 8. Various flow conditions (sheet 1 of 5)





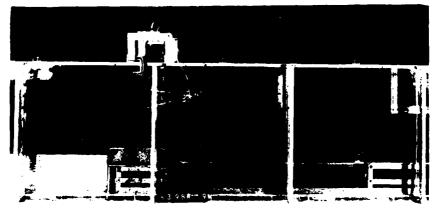
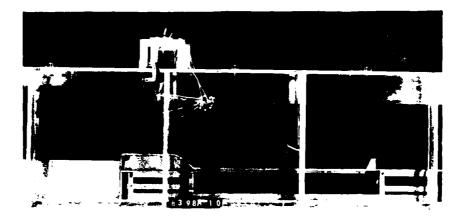
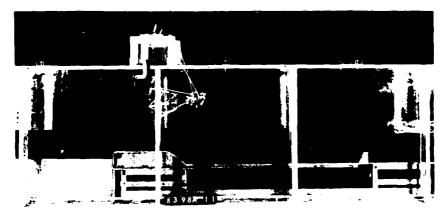


Figure 8. (sheet 2 of 5)





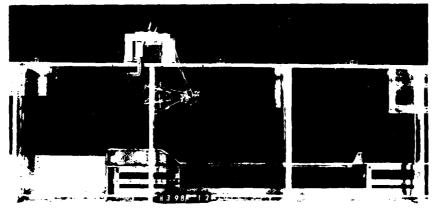
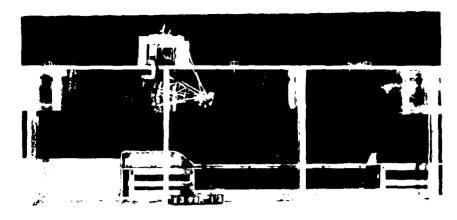
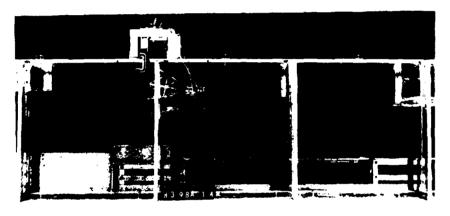


Figure 8. (sheet 3 of 5)





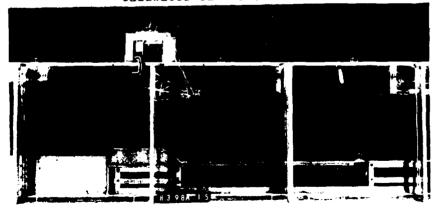


Figure 8. (sheet 4 of 5)

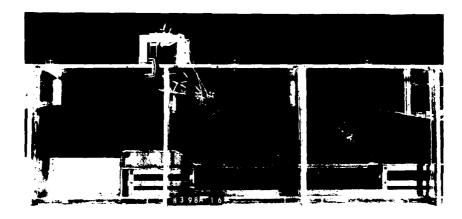


Figure 8. (sheet 5 of 5)

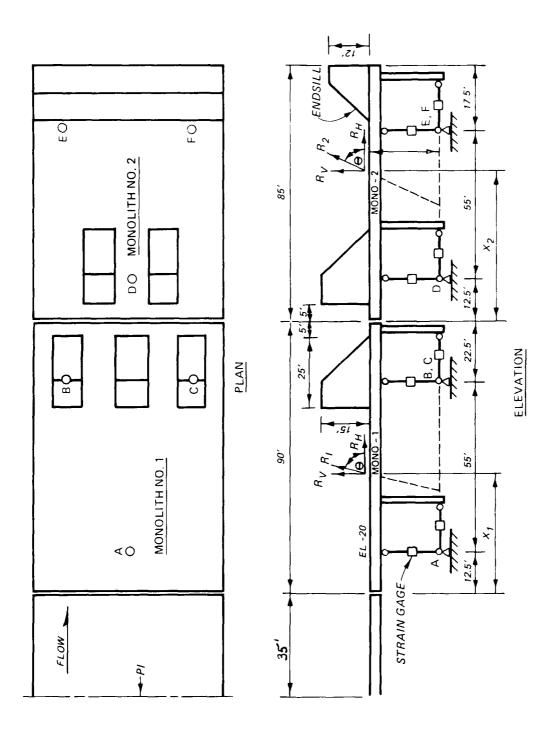


Figure 9. Type 2 monolith design

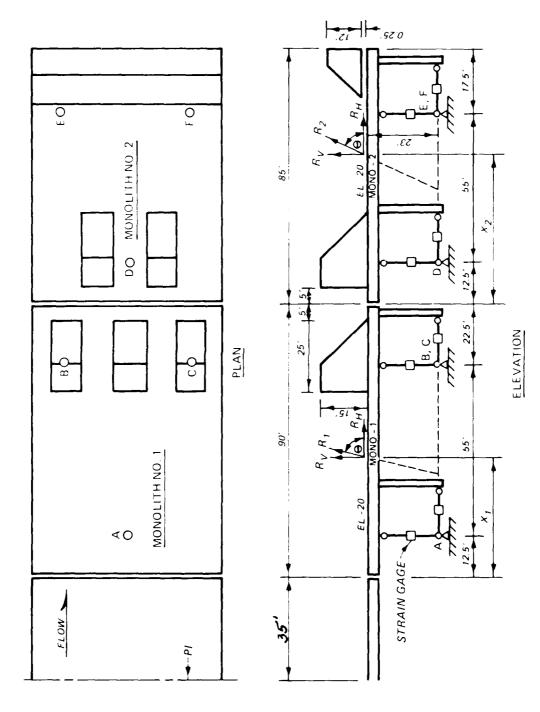
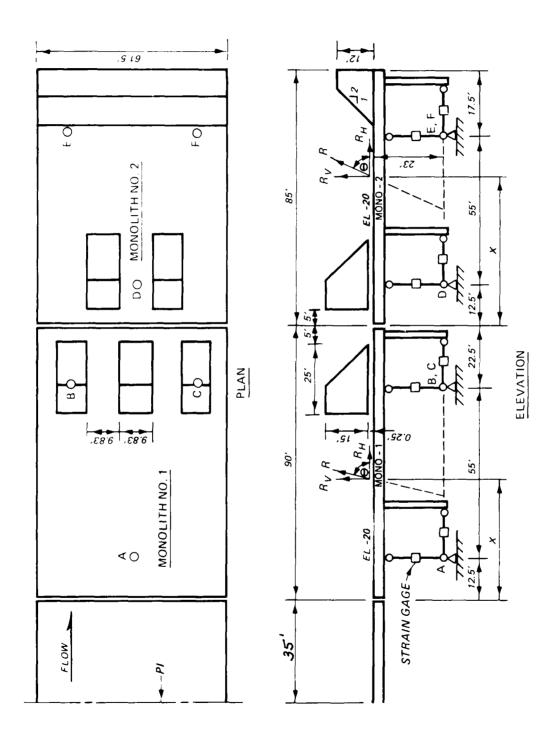
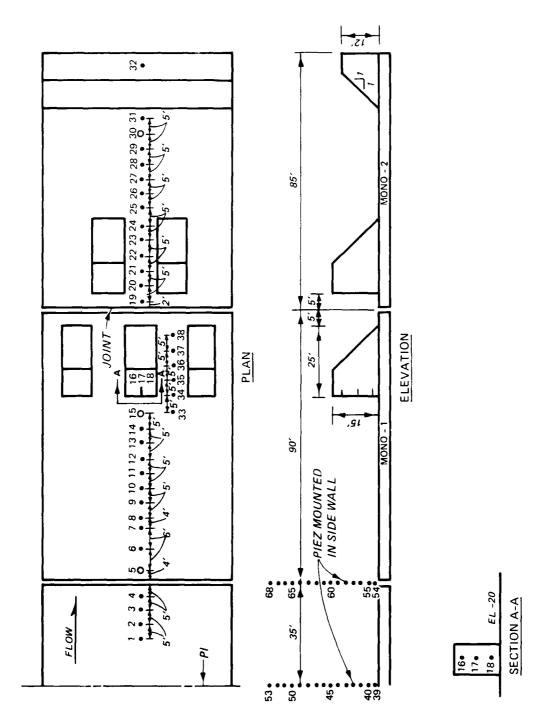


Figure 10. Type 2 monolith design end still detached from monolith No. 2



Type 2 monolith design baffles detached from monoliths Figure 11.



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Figure 12. Piezometers and electronic pressure cells

	>	2	Ŋ	0	ιņ	5	2	0	0		
0	ELEV	17.5	16.	22.	22.	24.	25.5	26.	26.0		
	×	25	50	75	100	125	150	180	250		1
٥	ELEV	27.0	27.5	32.5	32.0	33.0	35.0	35.0			
	×	15	20	15	100	125	180	250			
•	ELEV	44.0	46.0	46.5	46.0	46.0	47.0	47.0		- 270 CFS/FT	
	×	25	20	75	100	150	200	250		47; q = 430 47; q = 53 = 310	
										$G_o = 11$ ; $HW = 69.1$ , $TW = 35$ , $q = 430 \ CFS/FT$ $G_o = 10', HW = 65$ ; $TW = 47$ ; $q = 270 \ CFS/FT$ $TOP \ OF \ WALL \ EL 53$ $G_o = 75', HW = 69.1', TW = 26', q = 310 \ CFS/FT$ $E_{L-20}$	

EL, FT MSL

The action with the control of

Figure 13. Water-surface profiles (sheet 1 of 3)

DISTANCE FROM GATE SEAT, FT

•	X ELEV		25 9.0						
٥	ELEV	32.0	32.0	33.5	35.0	37.5	41.5	38.6	38.6
	×	0	15	22	20	8	350	200	250
	ELEV	34.0	37.5	37.0	36.5	37.5	37.5	39.5	38.3
	×	15	25	20	75	8	150	200	250
•	ELEV	43.0	43.0	47.5	45.0	45.5	45.5	46.0	45,9
	×	0	15	38	75	90	250	200	250
0	ELEV	60.0	60.5	61.0	61.0	60.5	61.5	61.8	
	×	0	25	75	3	150	200	250	

BASIC DATA

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Reseased Reseases

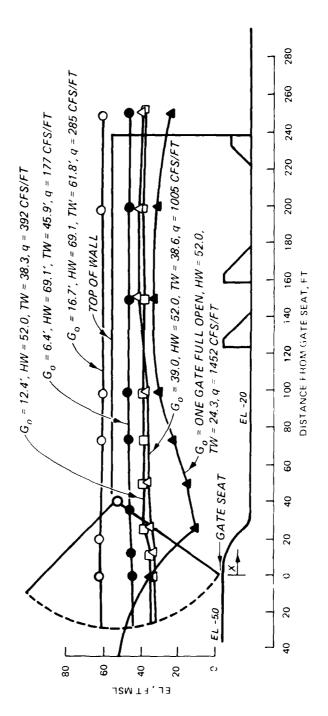


Figure 13. (sheet 2 of 3)

$G_o = 35', HW = 55', TW = 39', q = 950 CFS/FT$ $G_o = 35', HW = 69.1', q = 930 CFS/FT$ $TW = 53.0'$ $TOP OF WALL EL 53$ $G_o = 15', HW = 52', TW = 35', q = 400 CFS/FT$ $EL - 20$	40 60 80 100 120 140 160 180 200 220 240 260 280	DISTANCE FROM GATE SEAT, FT
~ I I \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \	09	
8 % 6 % o		

29.0 31.5 33.5 34.0 35.0 35.0

15 50 75 100 150 200 250

33.5 33.0 34.0 37.5 40.0 43.5 40.5 39.0

15 50 75 100 150 200 250

47.5 48.0 48.0 49.0 50.0 54.0 53.0

0 25 50 75 100 150 250

BASIC DATA

ELEV

0

Figure 13. (sheet 3 of 3)

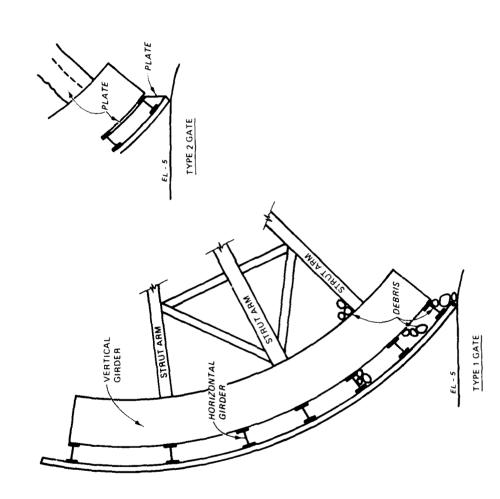


Figure 14. Debris in tainter gate

DA